

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S29	214	(382/152).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2005/01/06 14:49
S30	38	((382/152).CCLS.) and robot	US-PGPUB; USPAT	OR	ON	2005/01/06 14:57
S31	59	((382/151).CCLS.) and robot	US-PGPUB; USPAT	OR	ON	2005/01/06 14:59
S32	8	arimatsu-taro.in.	US-PGPUB; USPAT	OR	ON	2005/01/06 15:12
S33	175	watanabe-atsushi.in.	US-PGPUB; USPAT	OR	ON	2005/01/06 15:12
S34	8	382/141-154;901/47.ccls. and watanabe-atsushi.in.	US-PGPUB; USPAT	OR	ON	2005/01/06 15:12
S35	103	(robot) same (plural\$3 or multiple or dual or two or several or many) adj (video or camera or CCD or image or visual) same (workpiece or work-piece or work adj piece or part or model)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/01/06 15:14
S37	14	((382/154).CCLS.) and (reference or register\$3 or registration or teach\$3 or train\$3 or learn\$3) with (object or model or part or workpiece or work-piece or work adj piece) same robot	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/01/06 15:57
S38	130	(robot) same (video or camera or CCD or image or visual) same (predetermined or known or specifi\$2 or determined) near distance	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/01/06 16:00
S39	67	robot same (2-D or two-D or two-dimension\$2 or "2"-dimension\$2 or bi-dimensional or (two or "2") adj dimension\$2) with distance	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/01/06 16:25
S40	28	robot same (reference or register\$3 or registration or teach\$3 or train\$3 or learn\$3) same (video or camera or CCD or image or visual) same (predetermined or known or specifi\$2 or determined) near distance	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/01/06 16:42
S41	66	((901/47).CCLS.) and (registration or teach\$3 or train\$3 or learn\$3) with (model or part or workpiece or work adj piece)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/01/06 16:48

S43	157	(382/153).CCLS.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/06 16:54
S44	210	("382"/\$.ccls. "348"/\$.ccls. "356"/\$.ccls. "700"/\$.ccls. "901"/\$.ccls.) and robot\$3 same (camera or CCD or imag\$3 or video) same (position\$3 or locat\$4 or (three or "3") adj dimension\$2 or 3D or coordinate) with (orientation or posture or attitude or pose) with (object or workpiece or work adj piece or part or bin or pile\$1 or article or body)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/01/06 17:10
S45	48	robot\$3 same (camera or CCD or imag\$3 or video) same (orientation or posture or attitude or pose) with (object or workpiece or work adj piece or part or bin or pile\$1 or article or body) same (reference or model or register\$3 or registration or template or stored) with (compar\$5 or match\$3 or correlat\$3 or correspond\$3)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/01/06 17:33